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# ROUTING-STATE OBSERVATION AND MODIFICATION IN A LARGE NETWORK THANKS TO PULUMI-MANAGED API SERVICES IN AWS/ECS

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# AUTOPILOT-ROUTED

# Agenda

- Introduction
- Project overview
- Solution description
- Problems, issues and learnings
- Future
- Closure

# INTRODUCTION

# Daniel Caballero Rodríguez

- Principal SREngineer @ **Fastly**
- Previously part time (Devops) lecturer, Devops@**Schibsted** (now Adevinta), **NTT**, **Oracle**…
- *Eventual OSS contributions* (see tcpgoon)


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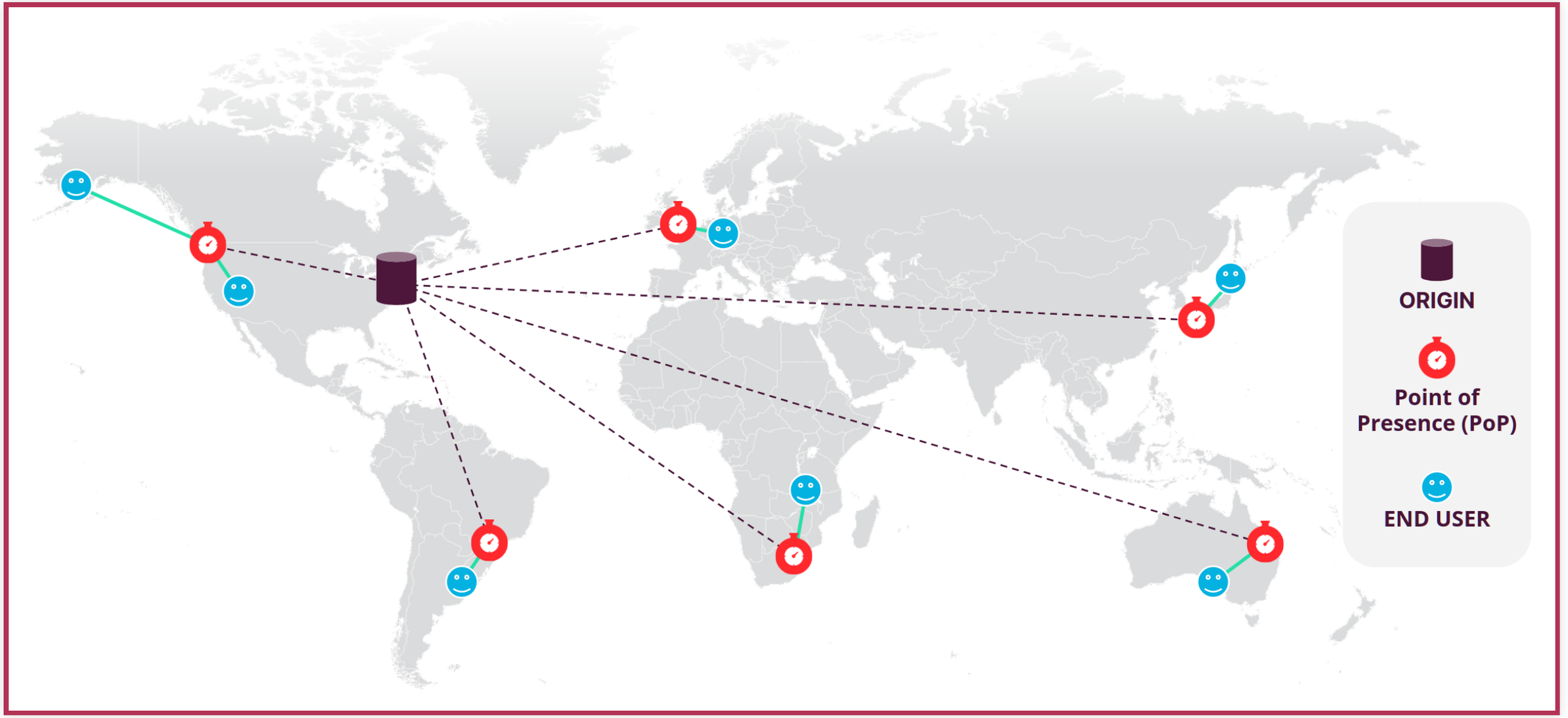
# OUR BUSINESS...



# WHAT MAKES US UNIQUE

**Software Defined Network** — **Programmable Edge** — **Customer Empowerment Philosophy**

## Edge Advantages

- Better performance
- Better UX
- More agility
- CI/CD integration
- Instant scale
- Greater control
- Heightened security
- Real-time visibility
- Reduce TCO
- Lower demand on origin
- Reduce time to deploy

# FASTLY AT A GLANCE

**>1.4Trillion**

Requests served daily[1]

**215 Tbps**

Edge Capacity[2]

**95%+**

Customer satisfaction score[3]

**13s**

Median Global Deploy Time[4]

**100**

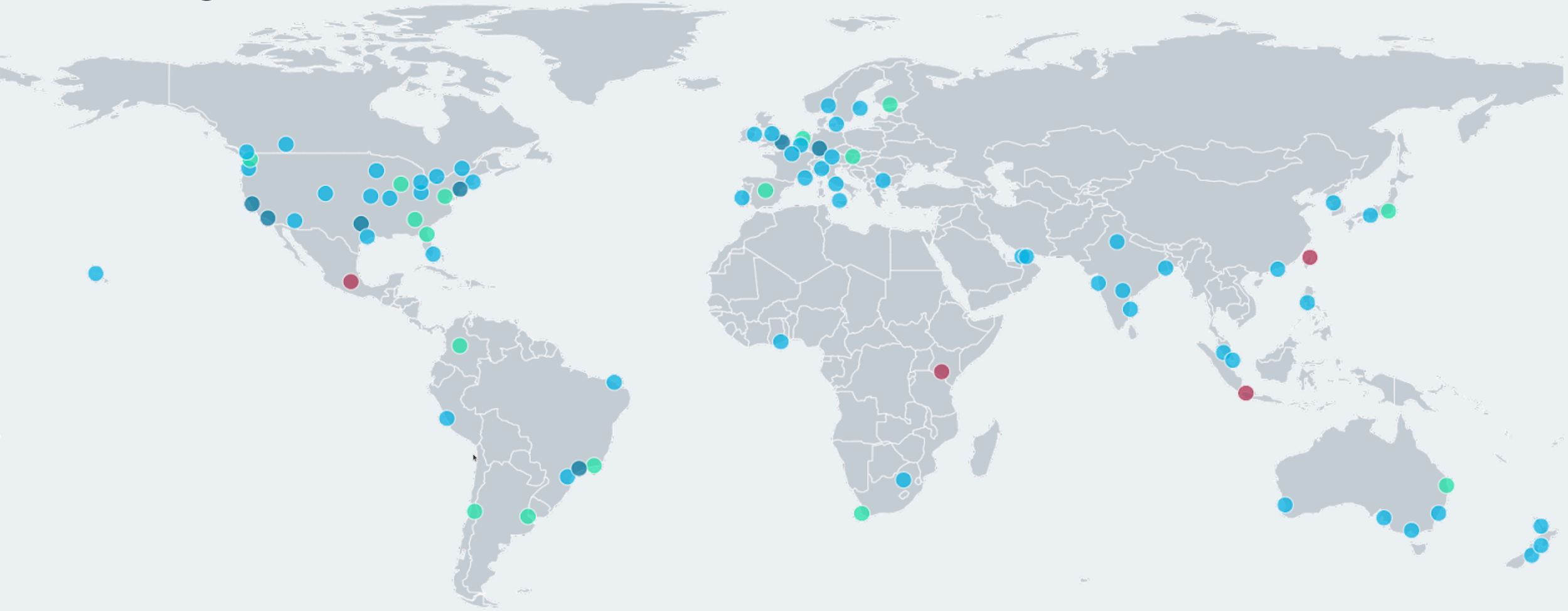
Number of POPs[5]

**>420 Billion**

Images optimized and delivered Per Month[6]

1. As of January 31, 2022
2. As of June 30, 2022
3. As of June 1, 2022
4. As of March 31, 2019
5. As of June 30, 2022
6. As of March 31, 2019

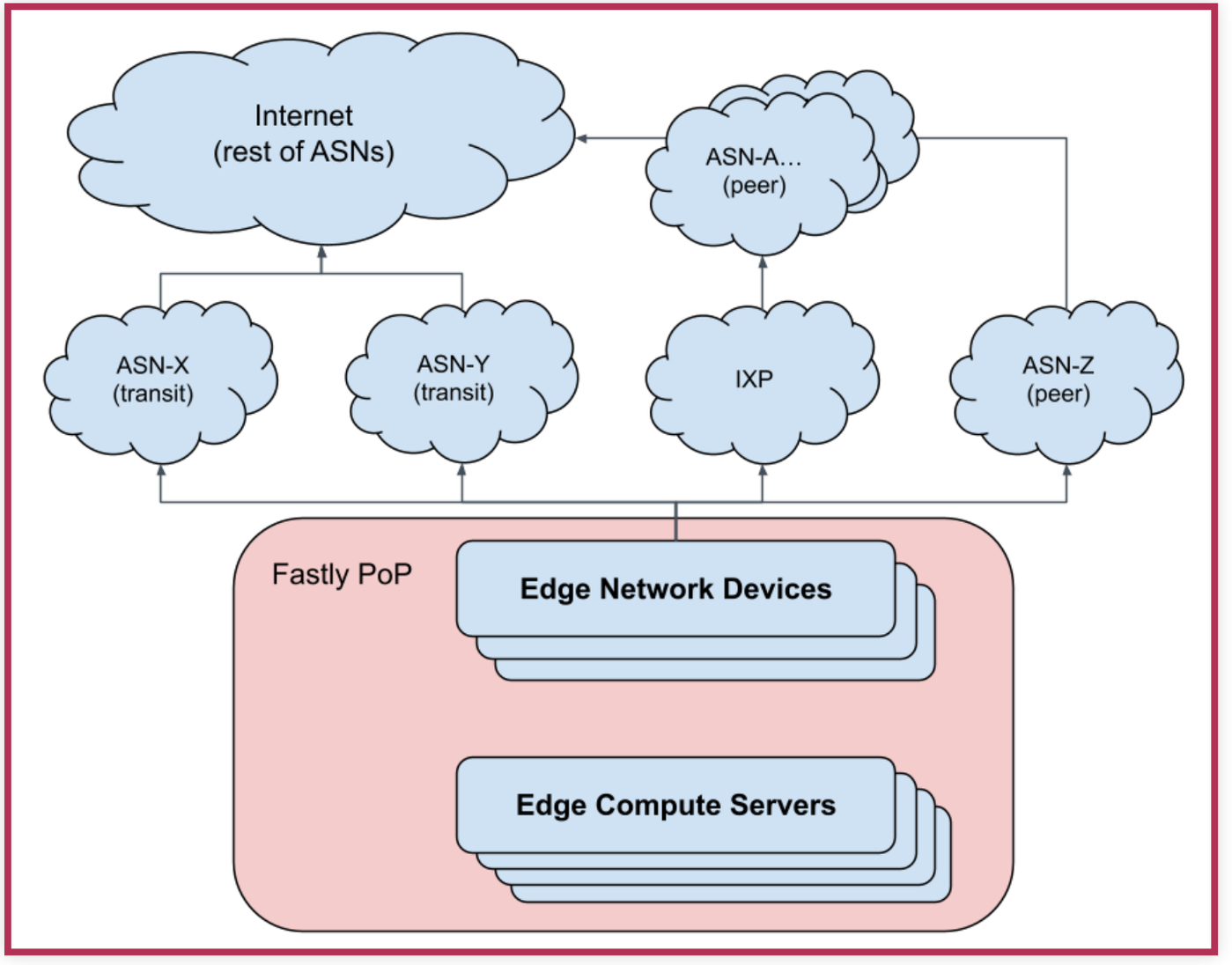
# Fastly Points-of-Presence (POPs)



Current POP  Current multi-POP  Planned new POP  Planned POP expansion

Map Updated June 30, 2022

# FASTLY AND EGRESS TRAFFIC ENGINEERING



# WE NEED AUTOMATION

# PROJECT OVERVIEW

# **Automation** in this problem domain is **not a new concept**

## How network automation helps Fastly support the world's biggest live-streaming moments

**Ryan Landry**
Vice President, Technical Operations

NETWORK PERFORMANCE REAL-TIME INSIGHTS STREAMING

Published March 10, 2020

One of the keys to a clean, clear live-streaming experience is properly managing network congestion — something our platform performs mostly automatically,

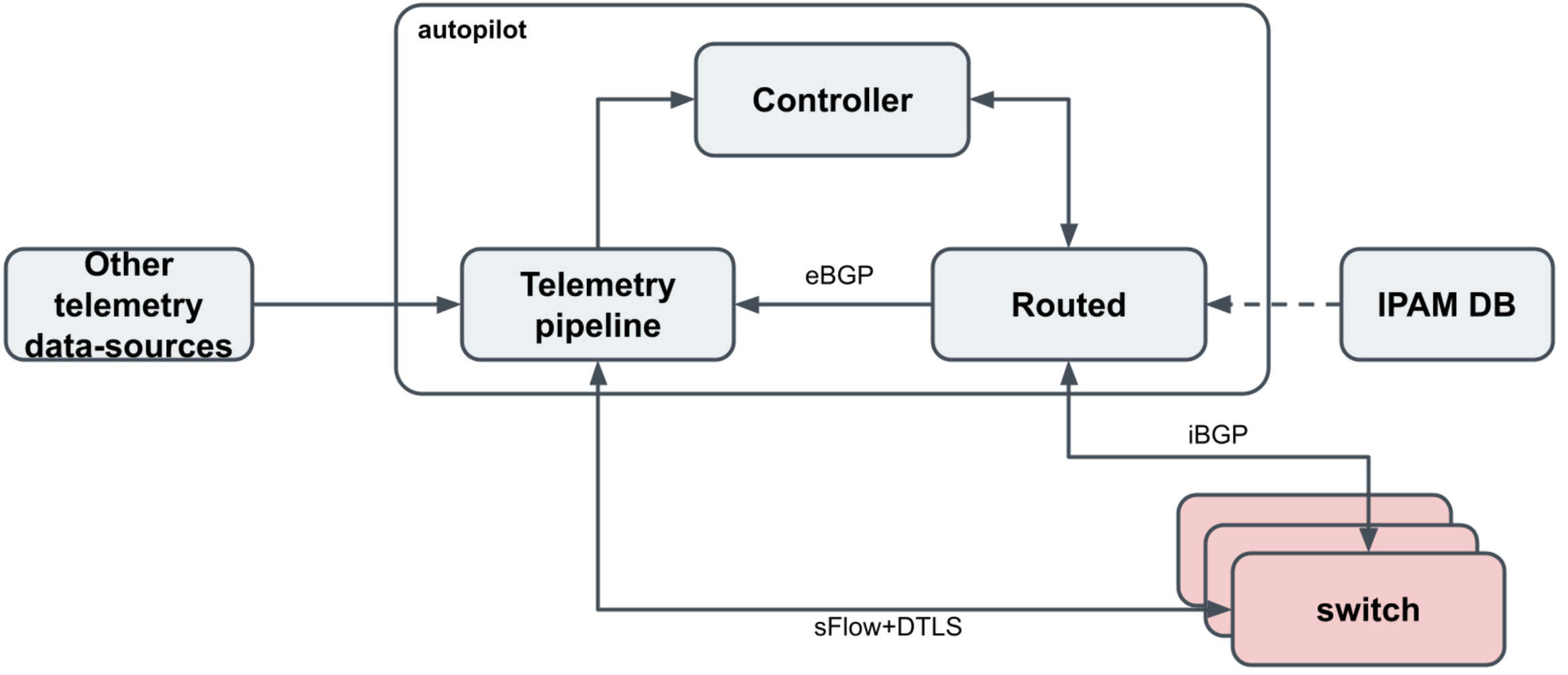
**Want to continue the conversation?**

https://www.fastly.com/blog/network-automation-helps-support-worlds-biggest-live-streaming-moments

# AUTOPILOT AS THE LAST ITERATION

- Developed and maintained by the *Network Control and Optimization* (**NCO**) team
- Initially around 6 people…
  - with different profiles (Software Engineers, Data Engineers, Network Engineers, SRE)

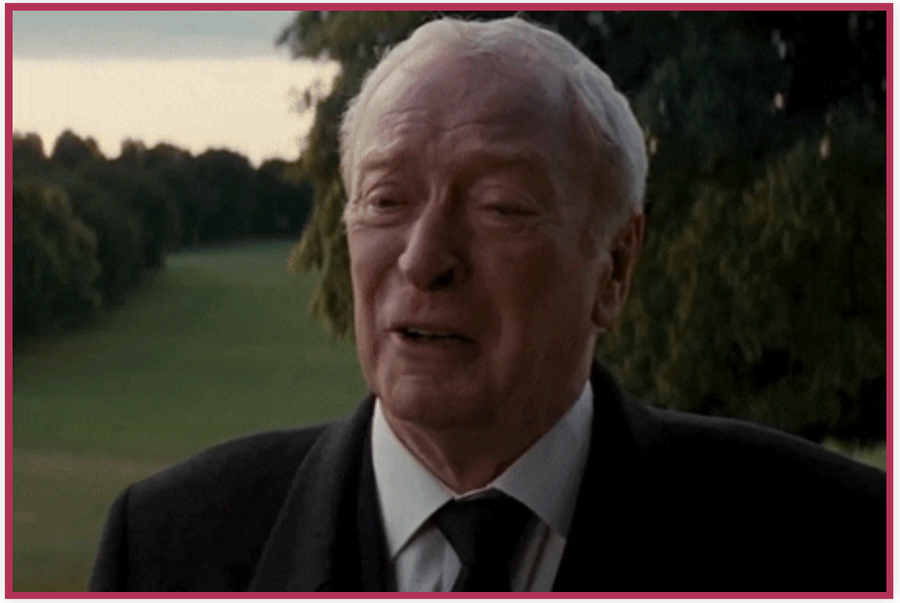
# AUTOPILOT AT HIGH LEVEL

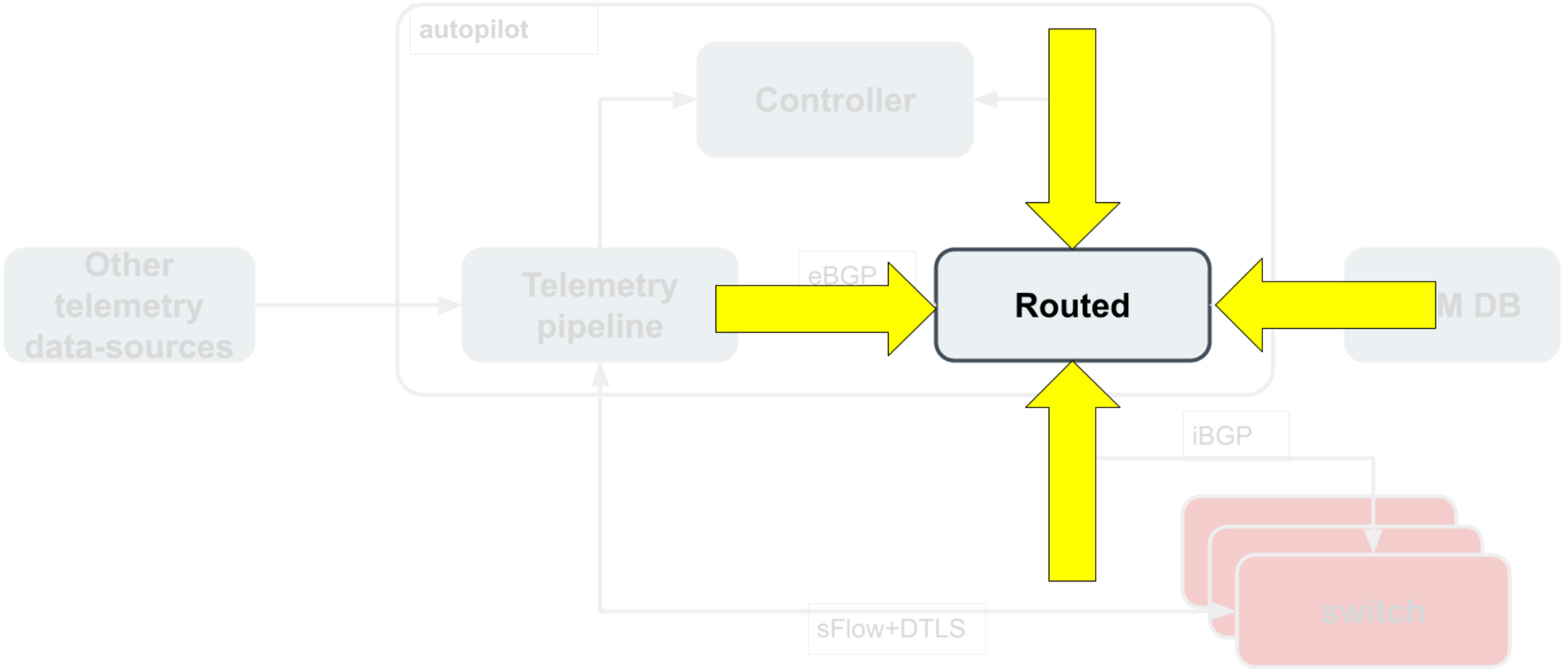


# OUR ABSTRACTION

```yaml
spec:
  releaseName: telemetry-kafka
  interval: 5m
  chart:
    spec:
      chart: telemetry-kafka
      version: 1.0.0
      sourceRef:
        kind: HelmRepository
        name: fastly-charts
        namespace: platform-flux
  values:
    kafka:
      replicas: 5
      volumesSize: 50Gi
      resources:
        requests:
          memory: 10Gi
          cpu: 500m
        limits:
          memory: 16Gi
          cpu: '4'
    zookeeper:
      replicas: 5
      volumesSize: 20Gi
    autopilotSites:
    - PoP-ID1
    - PoP-ID2
    - PoP-ID3
    - PoP-ID4
```

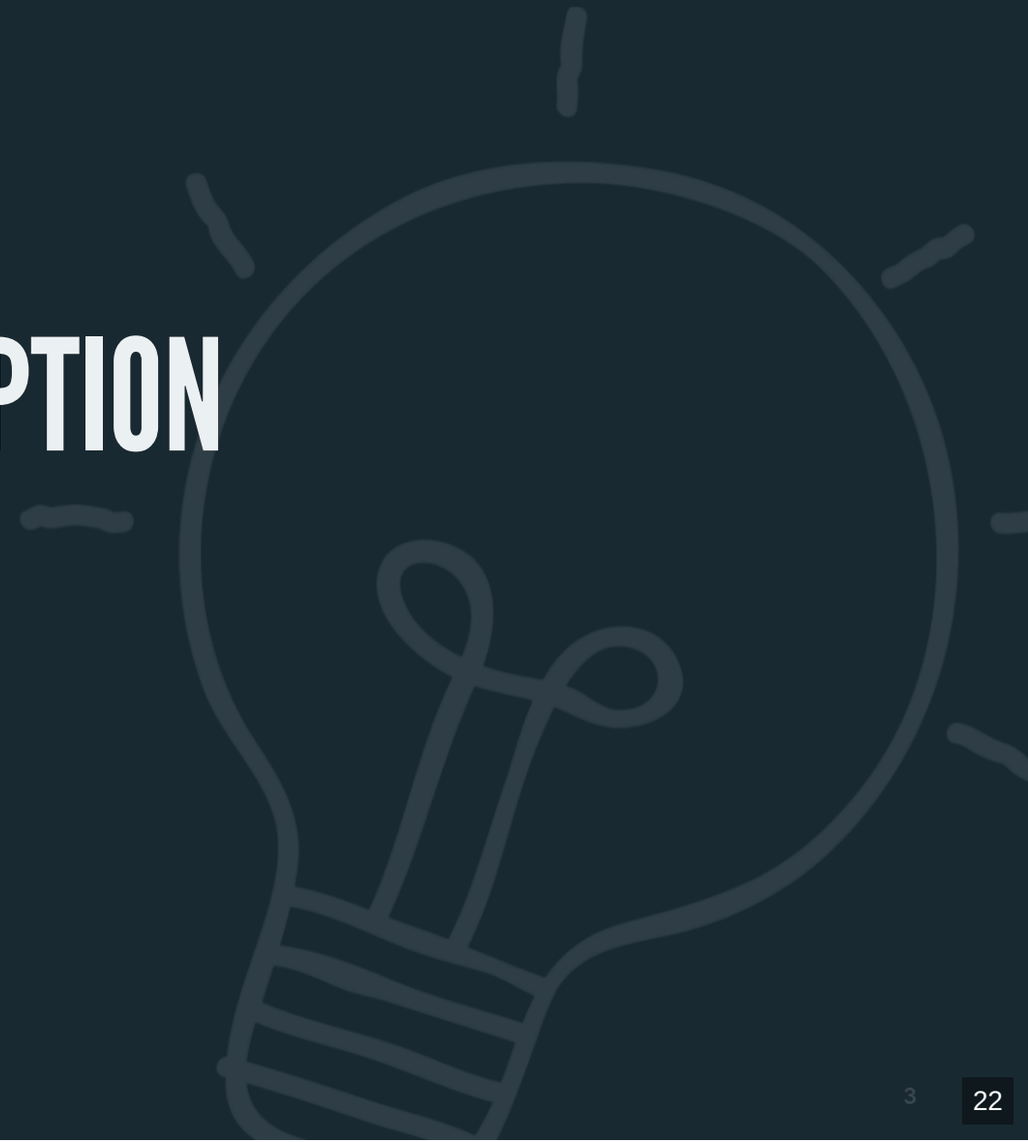
10 . 4



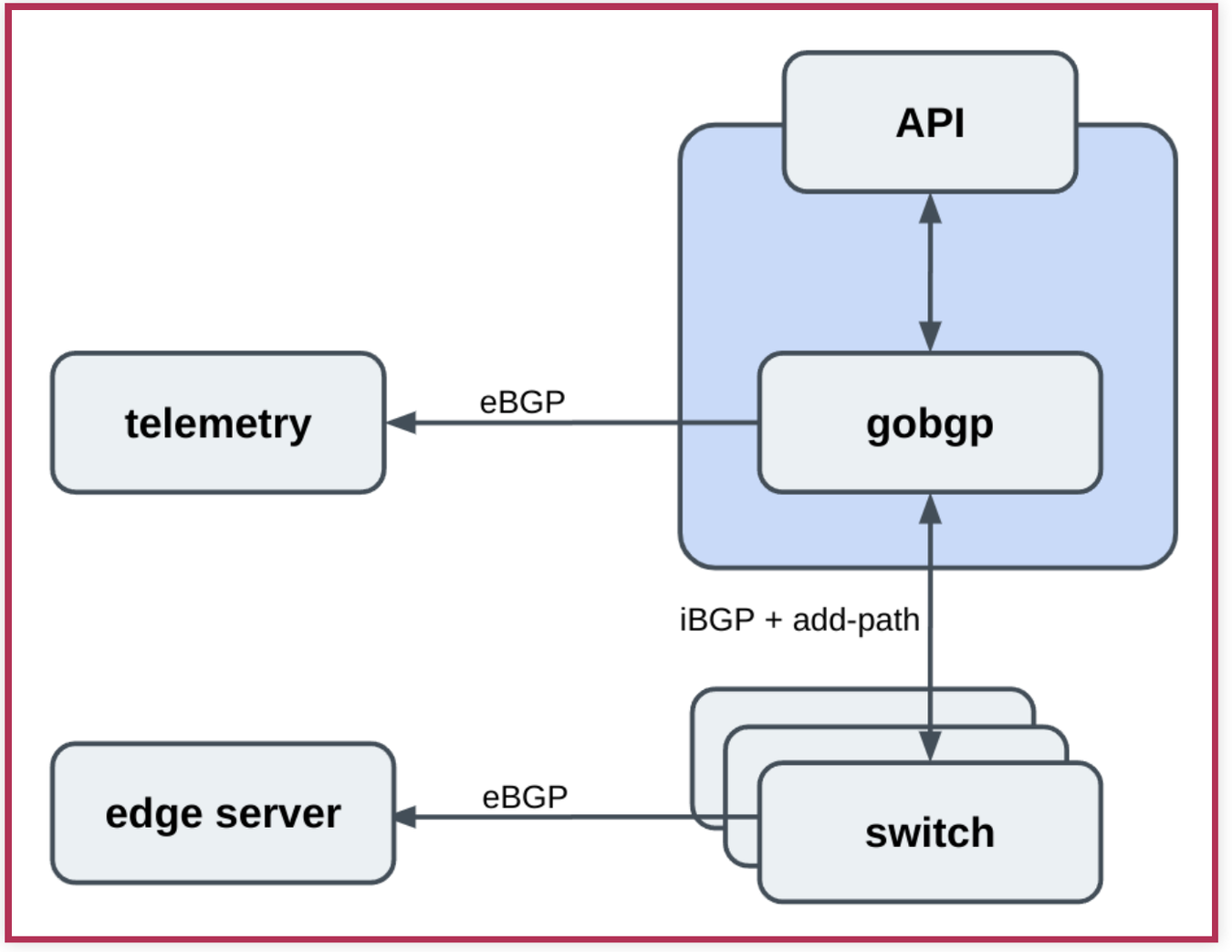


# THIS TALK IS ABOUT THAT NON-K8S PORTION

# SOLUTION DESCRIPTION



# AUTOPILOT-ROUTED



# WHY NOT K8S?

*This is our (BGP) routing daemon*

- **bird, networking ACLs, NATs and dynamic IPs** are not good friends
  - And our bird setup also requires **end to end IPv6**

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# K8S-APPROACH CHALLENGES

- Dual stack (IPv4/IPv6) was still in early stages…
- Not supported by the tooling that manages our multi-cloud k8s
- No *AWS NAT Gateway* equivalent for IPv6

# OTHER INTERESTING REQUIREMENTS

Critical, and quite large, in-memory DB… that takes a lot (>10m) to start/rebuild its state

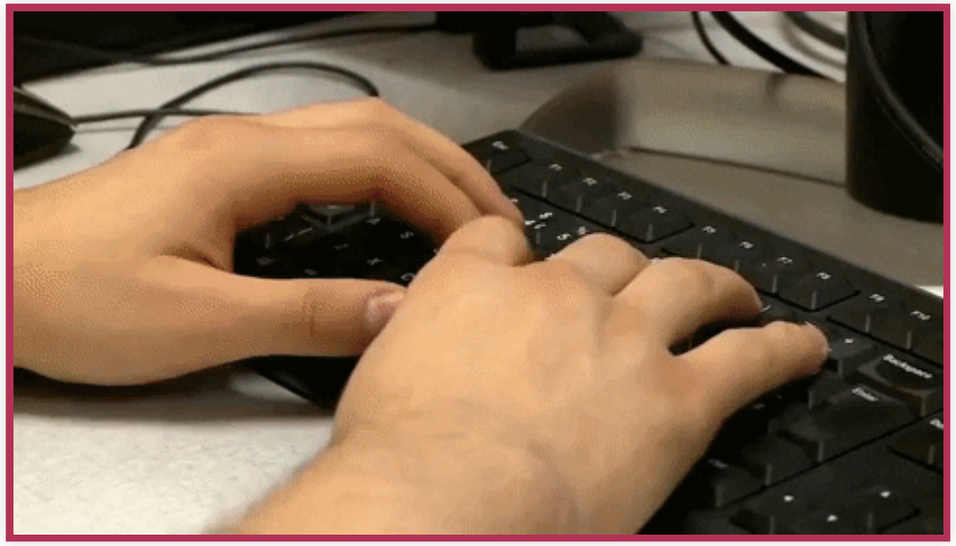
- 200 tasks/pods (2 per Fastly PoP)
- Each requiring about 4 CPU cores and more than 20G of RAM

# So we decided to isolate the complexity in some dedicated autopilot-routed infra

# WHY ECS?

- implicit decision, **AWS**:
  - GCP did not offer end to end **IPv6 with static IPv6 addresses**
- **containerized apps support**, to reduce the gap with the k8s services
- comes with an **app deployment solution**
- **less complex** than a dedicated k8s cluster
- **more flexible than** long running **chef**-managed machines

# And managing this infra/deployment also requires automation…




# Summarizing (some) IaC options

| Tool | Provider | Declarative? | Deployment tool? | Config-driven | Programmatic | Language |
|---|---|---|---|---|---|---|
| AWS API | AWS-only | N | N | N | Y | N/A |
| Cloudformation | AWS-only | Y | More or less | Y | N | JSON/YAML |
| Troposphere | AWS-only | Y | N | N | Y | Python |
| CDK | AWS-only | Y | Y | N | Y | Multiple |
| Terraform | Multiple | Y | Y | Y | N | HCL, JSON(v12) |
| Terrascript | Multiple | Y | N | N | Y | Python |
| Pulumi | Multiple | Y | Y | N | Y | Multiple |

# WHY PULUMI?

- Team with software engineering skills and already had some infra managed by Pulumi
- Terraform was not well standardized at Fastly
- Pure-code approach to discover configuration (rather than custom data sources)

PRODUCTS & TECHNOLOGY

# CDK for Terraform Is Now Generally Available

Cloud Development Kit for Terraform (CDKTF) has reached its first GA release, adding full support for Go and providing a GitHub action to use with Terraform Cloud.

AUG 01 2022 | SARAH MACDONALD

# IAC AND STACKS

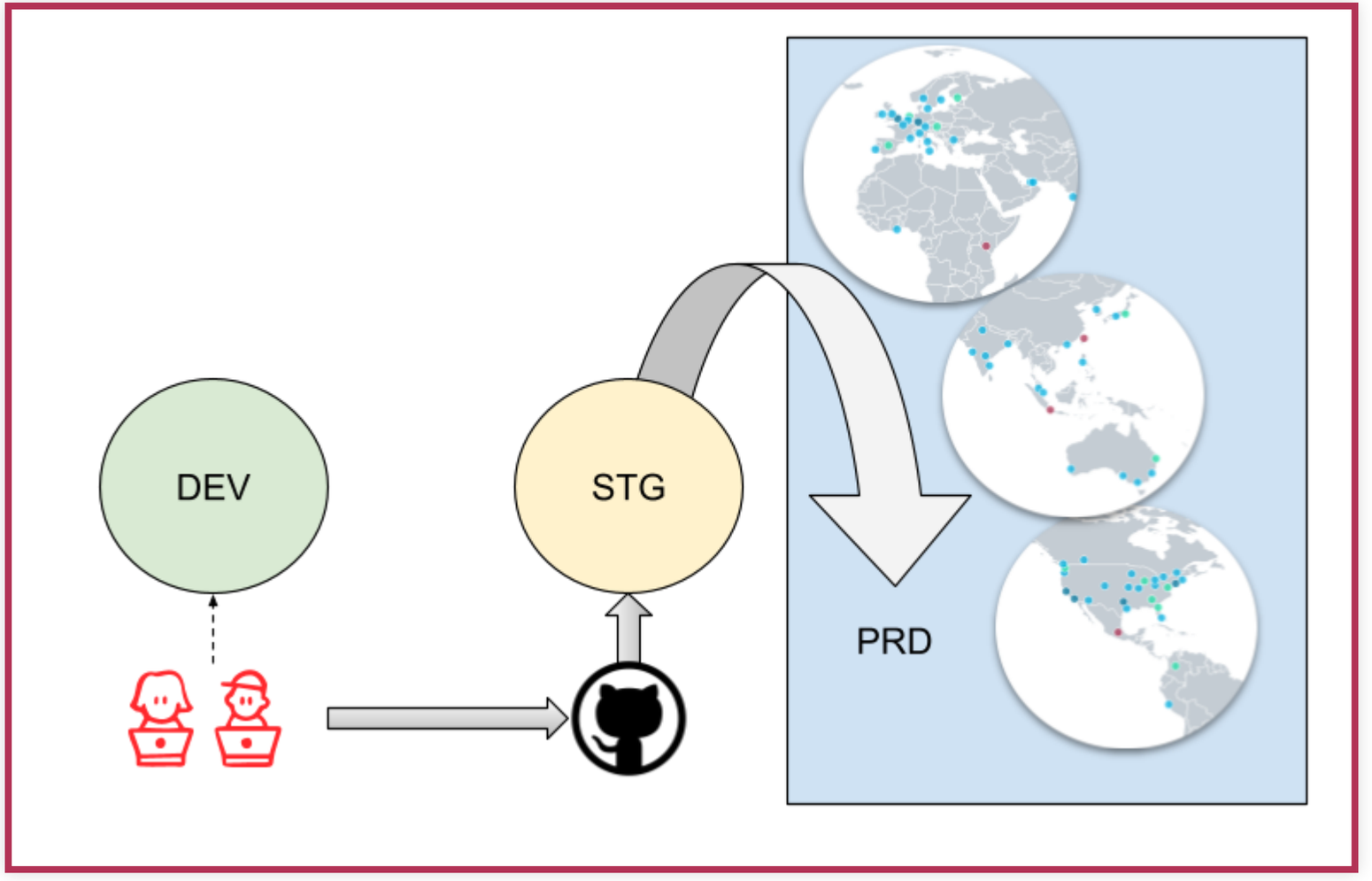
Given an environment (cluster) configuration:

- to support X Fastly PoPs
- in the most convenient AWS region

Creates:

- ECS cluster and some other GCP resources (ALBs, S3 buckets…)
- N immutable nodes distributed across AZs
  - with “persistent” static IPs (not an ASG)
- and X ECS tasks using host networking

# ENVIRONMENTS AND DEPLOYMENT FLOW



# OBSERVABILITY

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# PromCon 2018

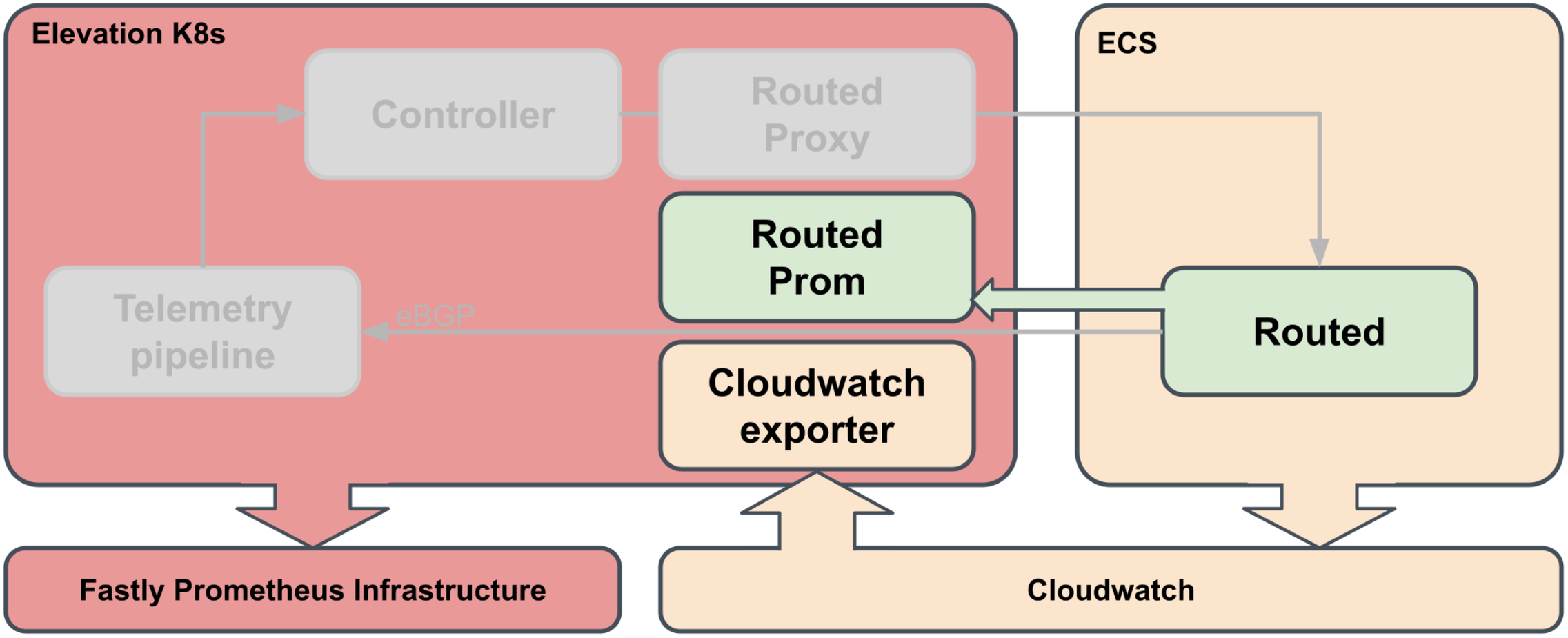
## Monitoring at Scale: Migrating to Prometheus at Fastly

**Marcus Barczak**
Fastly

DAY 2 - FRIDAY, AUGUST 10

https://prometheus.io
https://promcon.io/2018-munich
@PrometheusIO / #PromCon2018

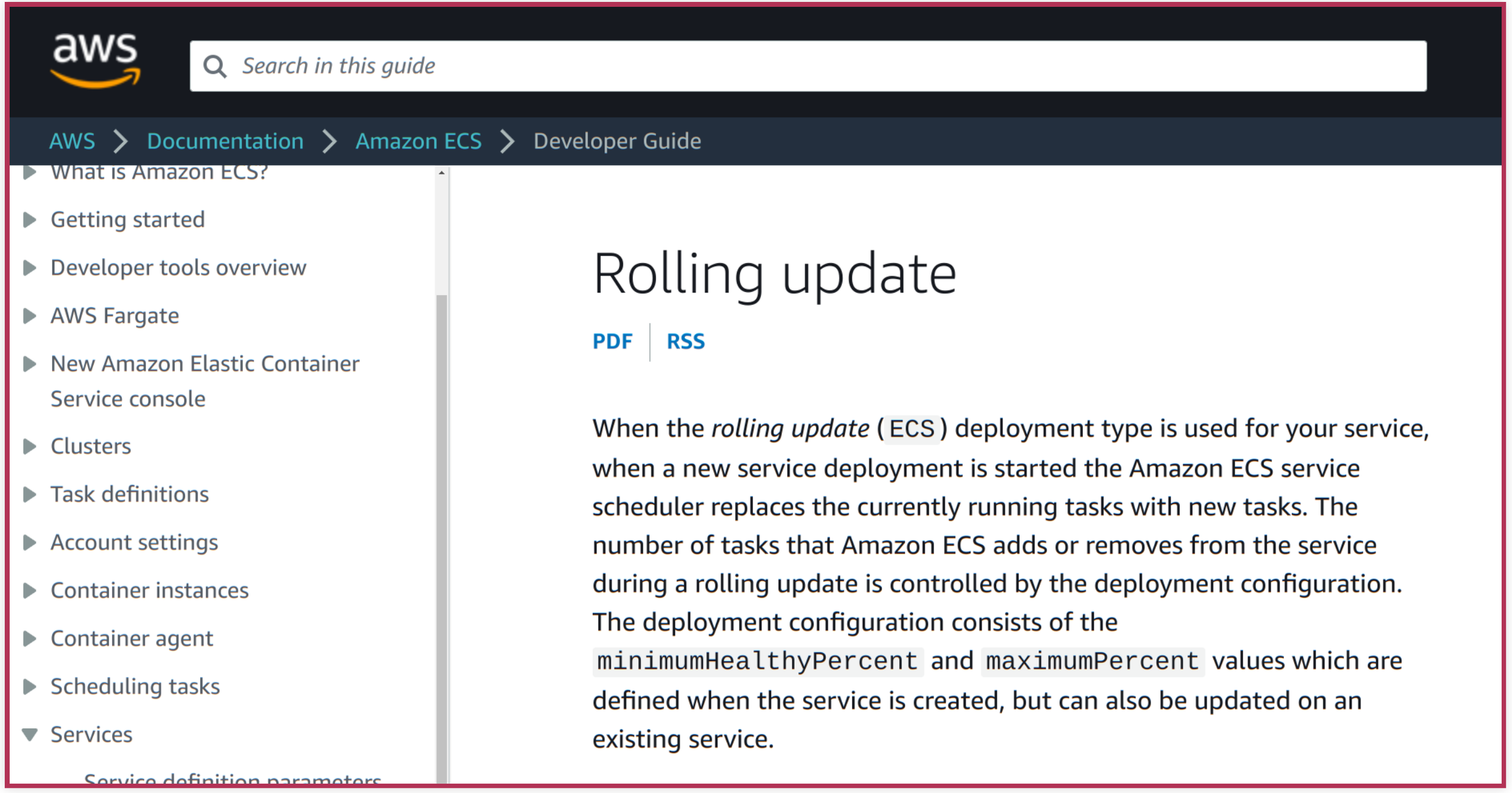
CLOUD NATIVE COMPUTING FOUNDATION



```yaml
apiVersion: helm.toolkit.fluxcd.io/v2beta1
kind: HelmRelease
metadata:
  name: autopilot-routed-prom-stg-awsuse2
  namespace: autopilot
spec:
  releaseName: autopilot-routed-prom
  interval: 5m0s
  chart:
    spec:
      chart: autopilot-routed-prom
      sourceRef:
        kind: HelmRepository
        name: fastly-charts
        namespace: platform-flux
      version: 0.0.4
  values:
    autopilotSites:
    - name: pop1
    - name: pop2
    - name: pop3
    ...
    image:
      version: 67a7485bd192-3177
    promRetention: 1d
    resources:
      limits:
        cpu: "4"
        memory: 4Gi
      requests:
        cpu: "1"
        memory: 1Gi
    routedIPs:
    - ip.1
    - ip.2
```

# PROBLEMS, ISSUES AND LEARNINGS

# ISSUE 1: NON DISRUPTIVE UPGRADES



*Incremental ECS tasks replacement almost out of the box…*

But node changes (ami, sizing) in absence of ASGs?

*pulumi (and terraform) pushes desired state to all managed resources*

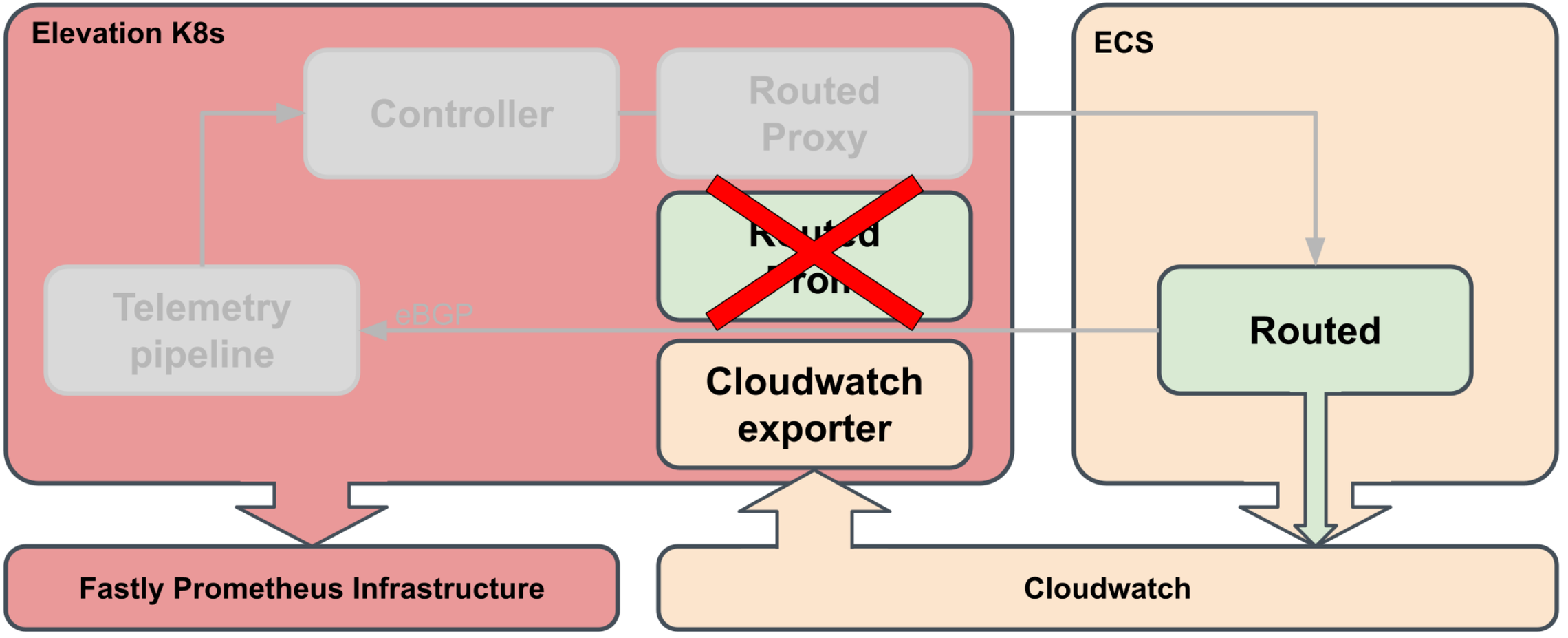
```python
def _get_servers_definition(
    self, num_instances, aws_instance_type, aws_instance_ami
):
    """Returns the final server configuration bearing in mind
    we only want to push some properties to a portion to the cluster,
    to avoid affecting all VMs concurrently / the entire cluster availability.
    This means the desired state will only become the actual one after a couple
    of deployments, simulating a rolling upgrade of the cluster nodes.
    """
    # Discovering current list of servers
    current_servers = []
    current_servers_definition = []
    try:
        current_servers = ec2.get_instances(
            instance_tags=DEFAULT_TAG, filters=[], instance_state_names=["running"]
        )
        current_servers_definition = [
            self.RoutedServer.from_id(i, instance_id)
            for i, instance_id in enumerate(current_servers.ids)
        ]
    ...
    return self._update_one_server_at_most(
        resized_servers_definition, aws_instance_type, aws_instance_ami
    )
```

# ISSUE 2

```
$ ENV=prd-na make deploy
```

Many ECS tasks and managed resources in a single stack…

# ISSUE 3: APP METRICS TO PROMETHEUS VIA CLOUDWATCH



But:

- Cloudwatch **specific instrumentation or sidecar** for each task
- Scraping custom cloudwatch metrics per task is **expensive**
- **scrape time** was a problem

*We still use `cloudwatch_exporter`, but just to import*
***AWS/ECS infra specific metrics***

# ISSUE 4: SCALABILITY

- Cluster horizontal scalability is complicated given the requirements
- Huge EC2 machines help with vertical scalability
- But less options to pick the right CPU/mem ratio

# ISSUE 5: PERFORMANCE

*we were initially not promoting CPU limits per service, thinking that we would maximize node CPU usage*

That was actually hurting performance

And CPU sets could be even better than shares

# ESSENTIAL CONTAINERS (DAEMON SETS)

*Don’t do this at home…*

Improved node recovery times, but only makes sense:

- we want one task per service and node
- cluster is dedicated for this application

# FUTURE

# CURRENT SETUP IMPROVEMENTS

- Migration to ARM for cost reduction
- Migration from Amazon ECS-optimized AMI to Bottlerocket

# BUT WE STILL WANT K8S

# Unified developer/ops experience

Unified developer/ops experience

Workloads consolidation / costs

Unified developer/ops experience

Workloads consolidation / costs

Less dedicated infra to manage

# HOW?

- Custom NAT gateway
- dynamic BGP peers discovery
- IPv6 over IPv4
- BGP BMP…

# CLOSURE

# SUMMARY

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Fastly needs **network and systems automation**

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There may be very specific cases where **custom infra may be required**

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There may be very specific cases where **custom infra may be required**

**Using Pulumi to define cloud IaC and drive ECS deployments was good**

# QUESTIONS?

# Thank You!


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